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# INFRAMIX

## Press-Conference

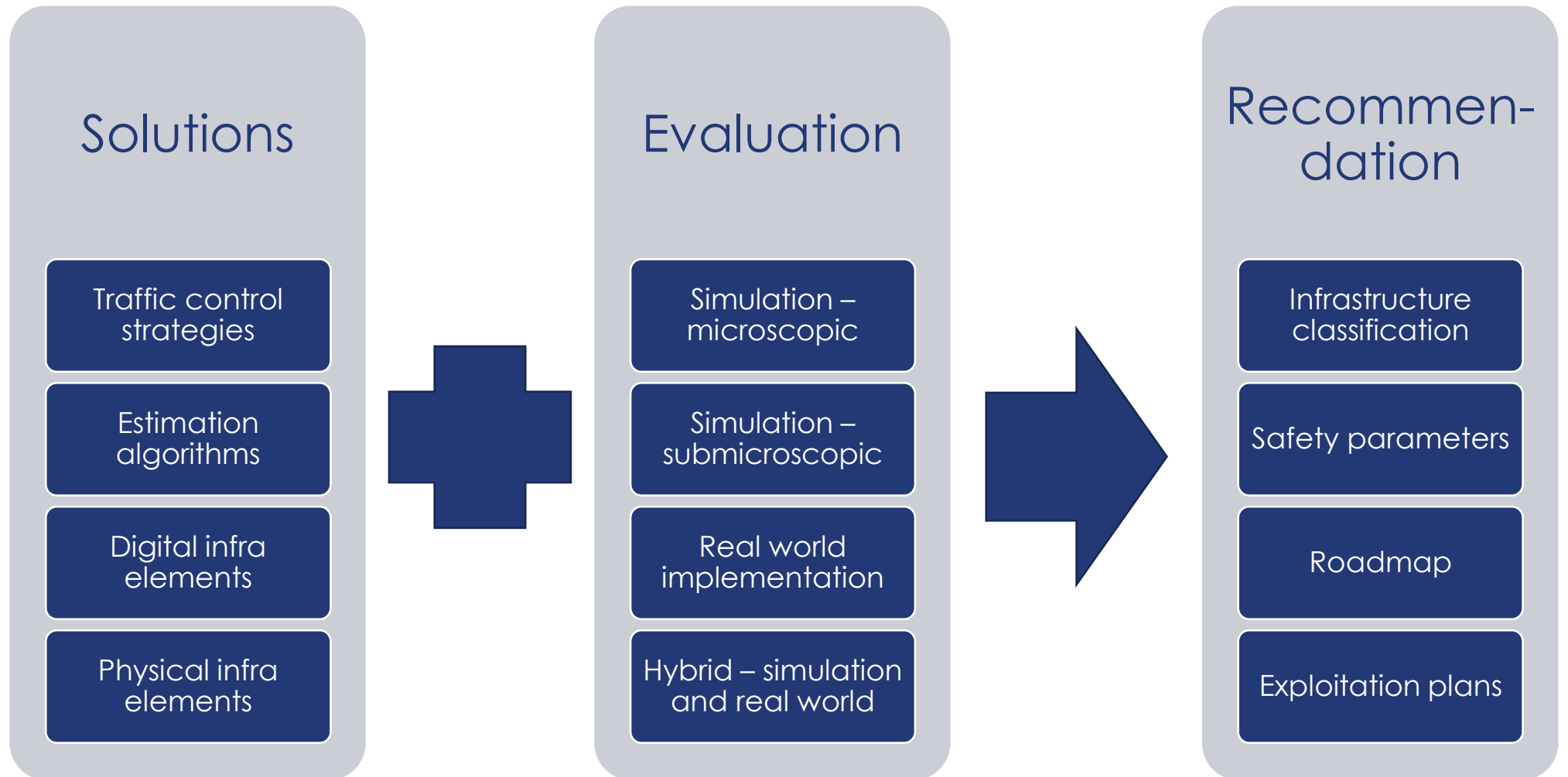
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Martin Russ / AustriaTech



This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 723016.

# INFRAMIX in a Nutshell



# INFRAMIX key achievements

- Focus on **3 motorway scenarios** (bottlenecks, workzone, lane assignment)
- Infrastructure **improves efficiency and safety in mixed traffic** environments
  - New traffic control strategies
  - New evaluation toolset (microscopic, sub-microscopic, hybrid – combination of simulation and real world)
- **New Infrastructure elements** tested
  - new (C-)ITS messages,
  - link between TMCs and TSPs,
  - new physical signs
- Infrastructure support (**ISAD**) **classes** have been defined
- **roadmap** for the next 10 years ahead....

# The future Role of Infrastructure

- **INFRAMIX** = one of many infrastructure related projects dealing with “**automation readiness**”
- Key platforms working on **future infra perspectives** – CEDR, ERTRAC, IRF/ERF, ASECAP, EU-EIP, ITF/OECD, Trilateral WG EU-US-JAP, CCAM Platform ...on topics like:
  - Physical and digital elements
  - Data quality
  - HD maps & location referencing
  - Specific scenarios: workzones, merging, handovers,...
  - Cooperative driving & Communication infrastructures
  - Legal requirements and digital road codes
  - A future „systems approach“ defining roles of users, vehicles and infrastructure
  - New mobility services (fleet operations) and new infra functionalities
  - .....

→ **Infrastructure as a key question and domain for future research initiatives!!!**

# Next steps

- More **Flexibility** – different situations lead to different requirements
    - „practical“ link to ODDs - Operational Design Domains
    - Which (minimum) elements could be combined to obtain the desired functionalities?
    - Data needs (maps, positioning, ...) & redundancy of elements/sensors
  - Wider perspective on **impacts & evidence**
    - „Co-benefits“, e.g. Environmental, service-orientation, network effects
    - Evaluate related costs & benefits
  - Integrate **legal framework**
    - Mandatory information/advice?
    - Quality & trust
  - **User perspective:** further feedback on user experience – does guidance work?
  - **COLLABORATION** (OEMs & Service Providers) & „**vehicle integration**“
- **Start implementing „no regret measures“** (along a common Vision & Strategy)

**Martin Russ**

***austriatech***



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# INFRAMIX

## Press conference

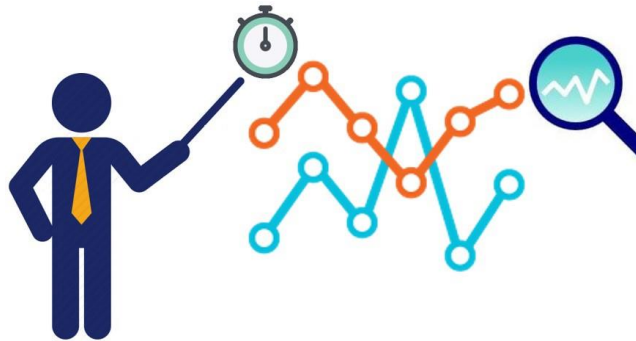
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**Dr. Panagiotis Lytrivis / ICCS**



# Introduction

- INFRAMIX implemented **significant innovations** in the area of **road infrastructure** and how this infrastructure can **support** the gradual insertion of **automated vehicles** in existing traffic.



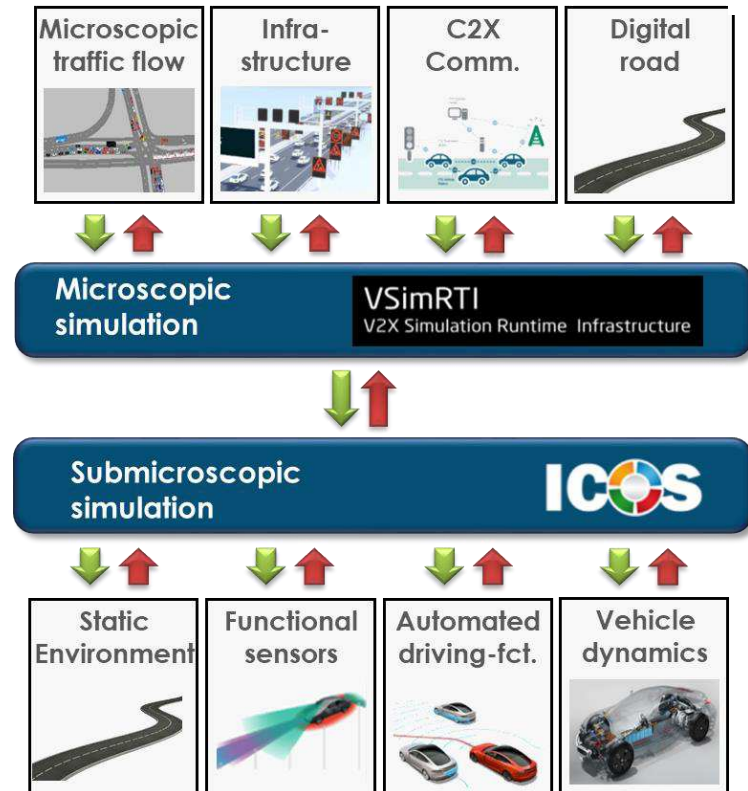
- The introduction of **AVs** is expected to **disrupt** existing traffic so it is important at the beginning of the transition period to focus on **maintaining at least** conventional traffic's **safety** and **efficiency**.
- In the longer term the target is to **enhance safety**, traffic **efficiency** and **comfort**.





# Communication, road signs, simulation

- The project implemented the latest C-ITS **communication** standards, working closely with **standardization** working groups.
- The project surveyed the road signs to see if they cover the needs of the co-existence of conventional and automated vehicles and **proposed a new traffic sign** for indicating the lane dedicated to automated vehicles (AVs).
- Advanced **simulation** tools were implemented:
  - A **co-simulation environment** coupling **microscopic** with **sub-microscopic** simulation
  - **Hybrid testing**: use of a real autonomous vehicle coupled with **virtual mixed-traffic**, giving us the opportunity to emulate critical virtual traffic situations in a **safe testing environment** with the **real hardware**





- **Speed recommendations** had positive impact in terms of safety
- **Time gap adaptations** showed in some scenarios even up to 50% enhancement in traffic efficiency
- The **lane change recommendations** usually led to **under-utilization** of road capacity and created **riskier** traffic situations
- Variable speed limit could **dissolve congestion at bottlenecks** and increase traffic efficiency in average by up to 14%, even with low penetration rate of connected and automated vehicles

Employing connected & automated vehicles will **gradually** result in **less infrastructure equipment** (VMS, spot sensors) leading also to **less costs** (incl. maintenance)

# Infrastructure classification scheme (ISAD)

“E”: typical/conventional



“A”: most advanced

This scheme will **support** and **guide** road operators and authorities to **target investments** to **support** higher levels of **AVs** especially for mixed traffic in the transition period

	Level	Name	Description	Digital information provided to AVs			
				Digital map with static road signs	VMS, warnings, incidents, weather	Microscopic traffic situation	Guidance: speed, gap, lane advice
Conventional infrastructure	E	Conventional infrastructure / no AV support	Conventional infrastructure without digital information. AVs need to recognise road geometry and road signs.				
	D	Static digital information / Map support	Digital map data is available with static road signs. Map data could be complemented by physical reference points (landmarks signs). Traffic lights, short term road works and VMS need to be recognized by AVs.	X			
Digital infrastructure	C	Dynamic digital information	All dynamic and static infrastructure information is available in digital form and can be provided to AVs.	X	X		
	B	Cooperative perception	Infrastructure is capable of perceiving microscopic traffic situations and providing this data to AVs in real-time.	X	X	X	
	A	Cooperative driving	Based on the real-time information on vehicle movements, the infrastructure is able to guide AVs (groups of vehicles or single vehicles) in order to optimize the overall traffic flow.	X	X	X	X

# Users' appreciation

- Approximately **170 participants** from ITS stakeholders participated in relevant workshops and demonstrations.
- The majority of the participants believe that INFRAMIX developments will **bring positive changes** in traffic conditions (**safety** and **efficiency**) but they are unsure about the specific characteristics of this improvement.

Behavior change  
Willingness to use  
Perceived usability  **70%**

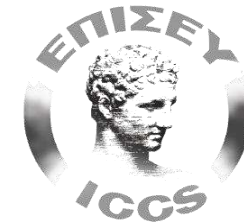


# Thank you for your attention!

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# INFRAMIX

## A Road Operator's Perspective

Bernd Datler  
INFRAMIX Press Conference  
May 27, 2020

# ASFINAG operates rural & urban highways with various traffic situations



< 20,000 vehicles/day

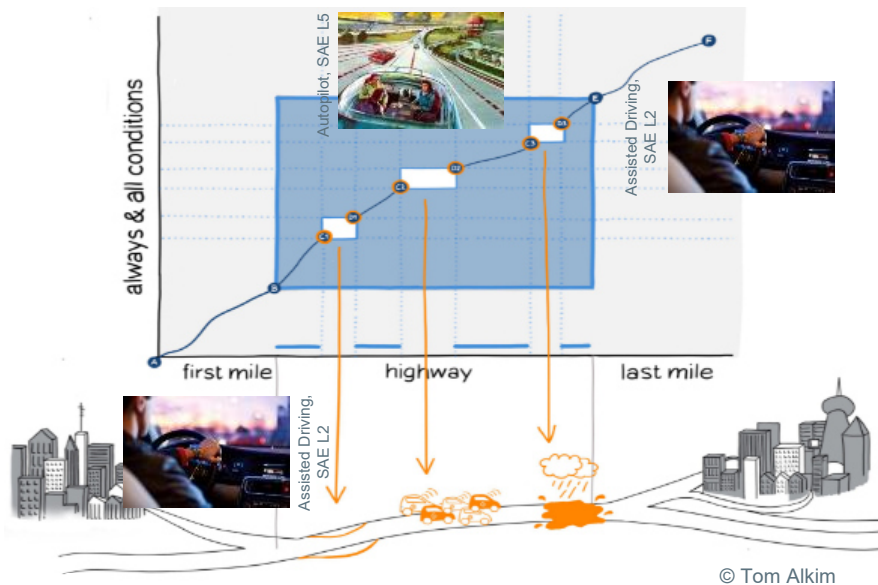


> 200,000 vehicles/day

# Challenges to enable safe and reliable mixed traffic flow

## Operational Design Domains for Automated Driving

## Different traffic situations



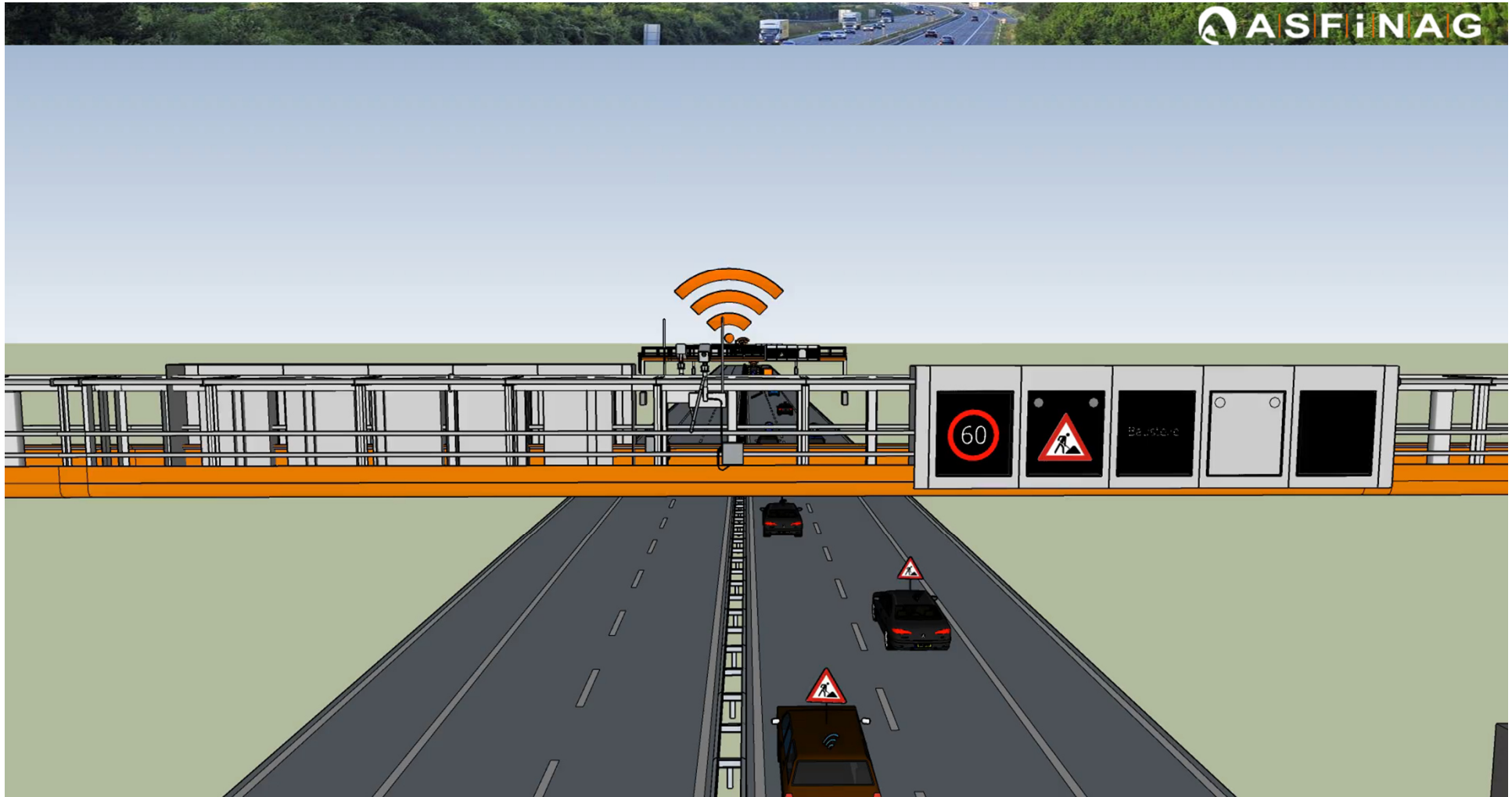
As long as ODD is fulfilled → AV can drive on its own

If ODD breaks down

→ Driver has to take over again -> potential negative effect on traffic flow

Number of ODD breakdowns (e.g. handovers) should be minimized





# ASFINAG and INFRAMIX

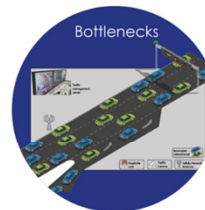


## ROADWORK ZONES



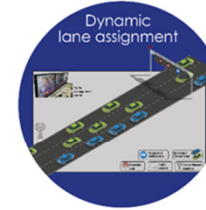
- Single Lane Closure (short-term constructions)
- New Lane Design (long-term constructions)

## BOTTLENECKS



- Automated vehicles driving behavior adaptation in real time at sags
- Lane-Change Advice to connected vehicles at bottlenecks
- Lane-Change Advice combined with Flow Control at bottlenecks for all vehicles.

## DYNAMIC LANE ASSIGNMENT



- Real-time lane assignment under dynamic penetration rate of automated vehicles
- Exceptional traffic situations, adverse weather conditions
- A conventional vehicle drives on a dedicated lane for automated vehicles.

## ASFINAG and INFRAMIX - Results

### 📍 Communication tests

- INFRAMIX message set was demonstrated successfully  
Next generation C-ITS messages (C-ITS Day 2) tested successfully for the first time in Europe

### 📍 Infrastructure Support for Automated Driving (**ISAD**) scheme was developed

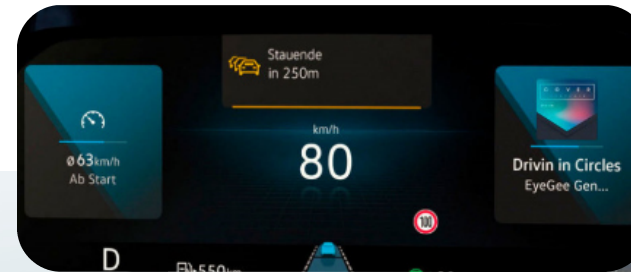
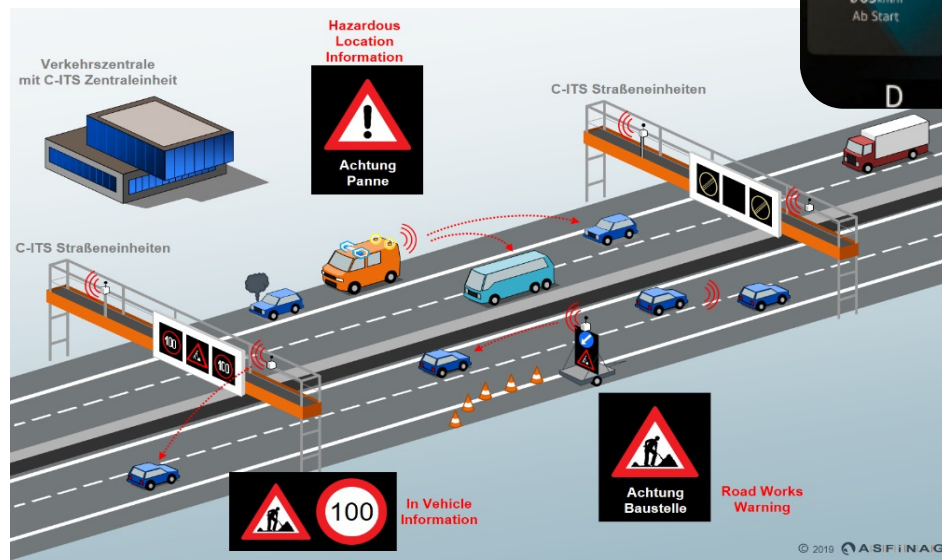
### 📍 Simulations

- INFRAMIX highlighted need for control strategies for higher penetration rates of AVs
- C-ITS is a key feature in these strategies

### 📍 Also the **safety aspect** is addressed by C-ITS which **shows great potential**

# Available traffic information services (C-ITS Day 1)

For cooperative connected vehicles



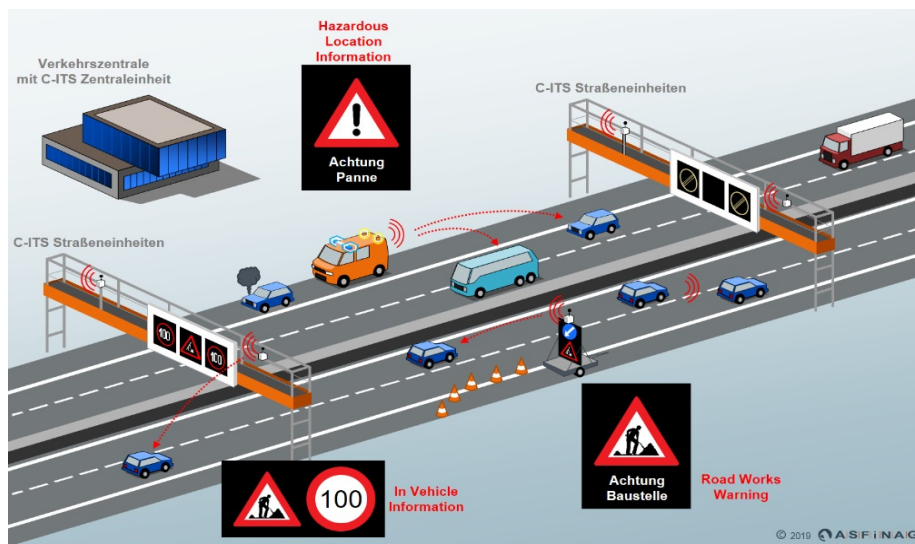
Sources: VW Newsroom & <https://www.youtube.com/watch?v=z3hN010mczU>

# Ongoing tests with series vehicles in Europe



# C-ITS Deployment in 2020

Day 1 according to C-Roads Catalogue



Day 2 according to ECo-AT extended Release 4.0\*

Free download

Use Cases C-ITS for Automated Driving



UC01: SAE level clearance for automated vehicles

UC02: Platoon support information for automated vehicles

UC03: Situation based distance gap for automated vehicles

UC04: Vehicle type and lane specific speed limit for automated vehicles

UC05: Vehicle type and lane specific speed recommendation for automated vehicles

UC06: Contextual emergency corridor information

UC07: Collective perception of objects on the road

UC08: Information about ITS-G5 equipped objects and persons on the road

UC09: Traffic situation awareness based on CAM

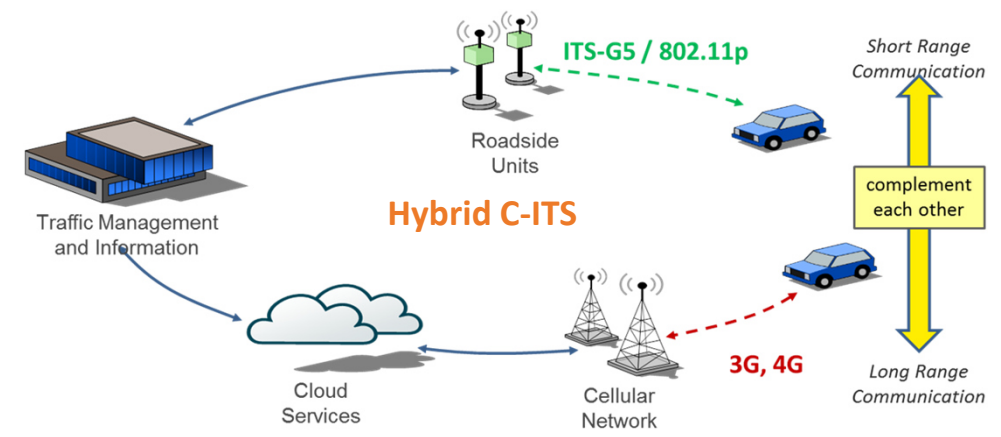
UC10: Long term road works warning

UC11: GNSS correction data

\*Successful Day2 tests (ITS-G5) were performed in 2019  
(see [https://www.inframix.eu/wp-content/uploads/D4.2\\_Demonstration-Phase-and-Data-Delivery-Report\\_v12-Final-Public.pdf](https://www.inframix.eu/wp-content/uploads/D4.2_Demonstration-Phase-and-Data-Delivery-Report_v12-Final-Public.pdf))

# Rollout in Austria

ASFINAG C-ITS activities:



Pilot:  
ECo-AT

Pre-Deployment:  
C-Roads Pilot Austria

Deployment:  
Austria



ECo-AT Spec (Day1)

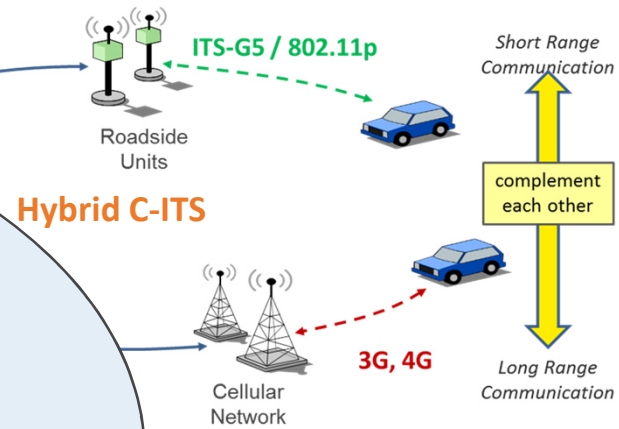
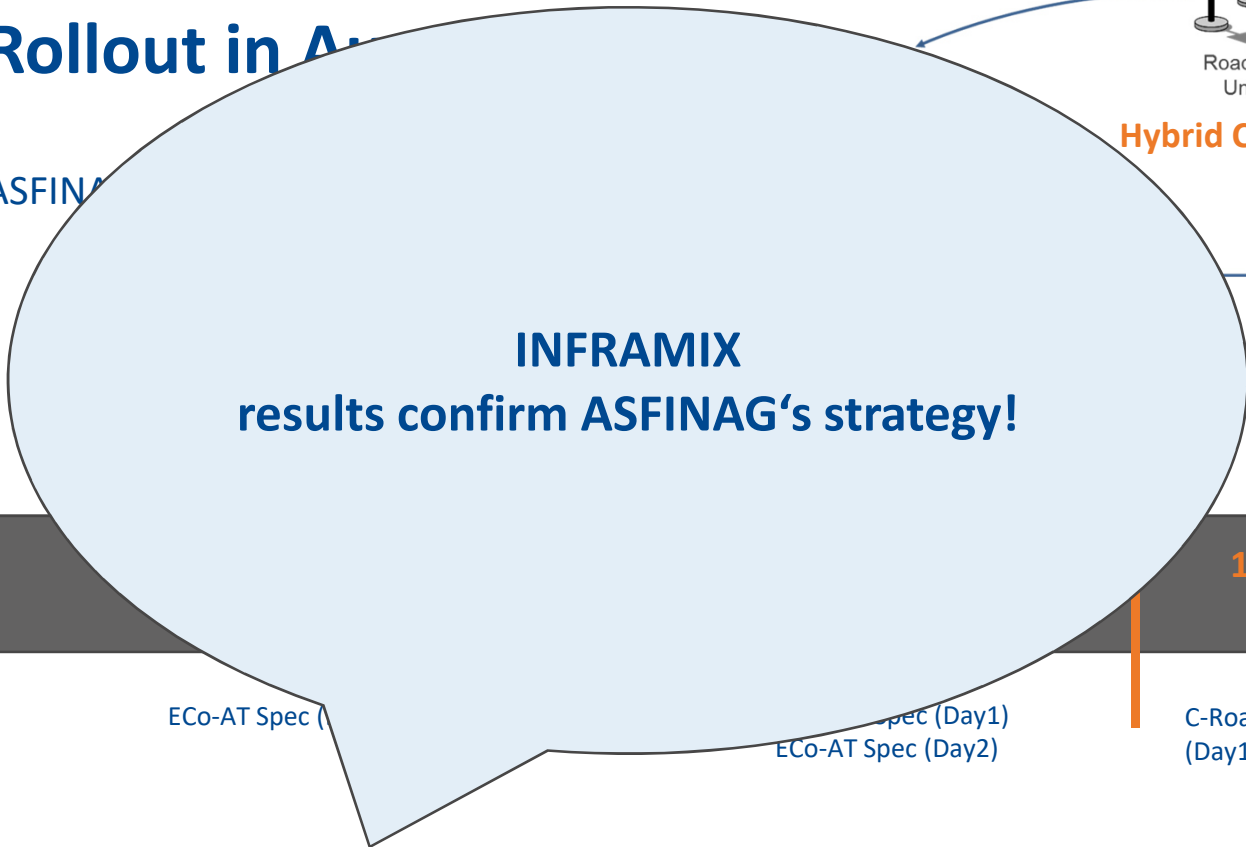
C-Roads Spec (Day1)  
ECo-AT Spec (Day2)

C-Roads Spec and extensions  
(Day1, Day2)



# Rollout in Austria

ASFINAG



deployment:  
Austria

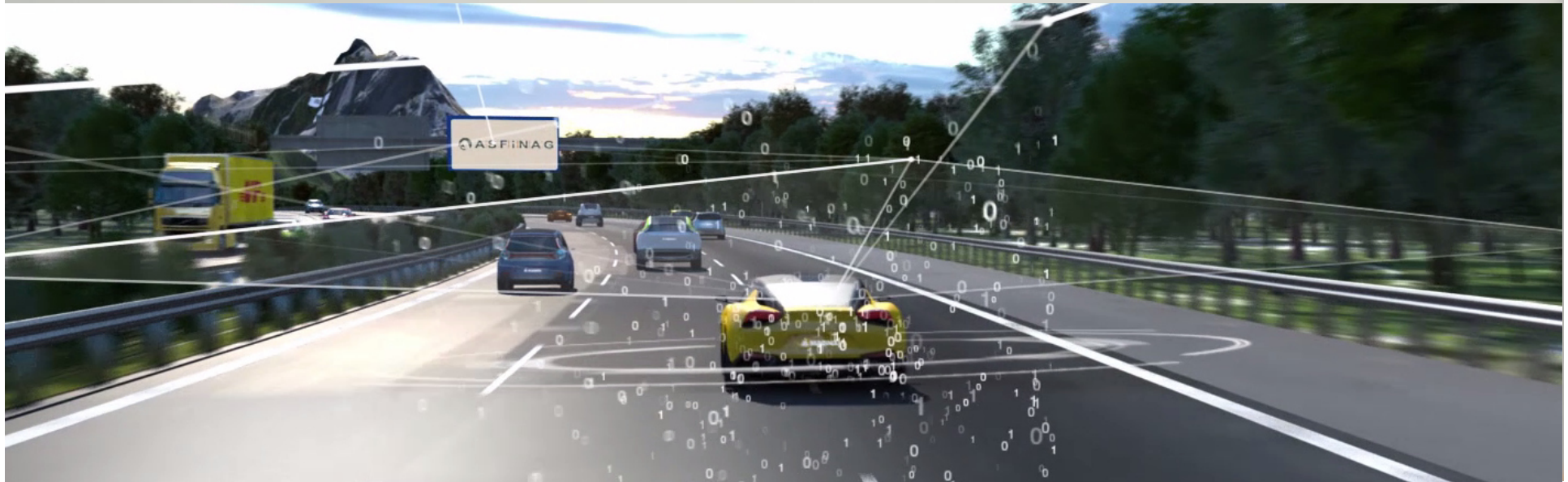
175 + 325 RSUs  
starting from 2021

ECo-AT Spec (Day1)  
ECo-AT Spec (Day2)

C-Roads Spec and extensions  
(Day1, Day2)







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